

GRAPE CS-ML DATABASE-INFORMED METHODS FOR CONTEMPORARY VINEYARD MANAGEMENT

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ABSTRACT

This work makes two significant contributions to the current status of viticulture technology studies. We start with a detailed look at the history and current state of computer vision, image processing, and machine learning applications in the wine industry. We provide a concise overview of recent advances in vision systems and methodologies by analysing case studies from a wide range of fields, including as crop yield estimation, vineyard management and monitoring, disease detection, quality evaluation, and grape phenology. Here, we zero in on the ways in which modern vineyard management and vinification procedures can benefit from the application of computer vision and machine learning. In the paper's second section, we introduce the brand-new Grape CS-ML Database, which contains photos of grape varieties at various stages of development alongside the relevant ground truth data (e.g. pH, Brix, etc.) collected from chemical analysis. The creation of useful solutions for use in smart vineyards is a primary goal of this database, and it is hoped that it will inspire academics in computer vision and machine learning to work on this problem. We showcase the database's potential for a color-based berry recognition application by comparing white and red cultivars across a number of machine learning methods and colour spaces, and providing a set of reference data for evaluation. The study finishes by pointing out some of the issues that will need to be resolved in the future in order to fully utilise this technology in the viticulture industry.

Keywords: Viticulture, Computer Vision, Machine Vision, Visual Computing, Image Processing, Machine Learning.

I. INTRODUCTION

The Internet is transforming the way people study and work, but it also leaves us vulnerable to grave security dangers due to the growing convergence of online and offline activities. The immediate problem that needs to be solved is how to recognise different types of network attacks, especially ones that haven't been observed before. Cybersecurity refers to a group of practises and procedures used to prevent harm to digital assets such as computers, networks, programmes, and data. There is both network security and computer security in place within a network security system. Firewalls, anti-virus programmes, and intrusion detection systems are all part of these networks' defences (IDS). Unauthorized actions, such as access, duplication, alteration, or deletion of data, can be difficult to detect without the assistance of an IDS [2].

External and internal incursions are both examples of security breaches. Misuse-based, also known as signature-based, network analysis is the most common type of network analysis used by IDSs, followed by anomaly-based and hybrid approaches. The goal of misuse-based detection systems is to identify malicious activity based on the characteristics of previously identified attacks [3]. They can be put to use for certain assaults without triggering an excessive number of false positives. On the other hand, administrators frequently need to manually update the database's rules and signatures. Misusing technology makes it impossible to prevent or detect new assaults (zero days).

An anomaly-based approach looks at typical network and system operation to spot outliers. Their ability to identify previously unknown assaults is a major selling point. Another perk is that unique normal-use profiles can be created for each system, application, or network, making it more challenging for attackers to determine which actions will go unnoticed. Information on which anomaly-based tactics raise an alarm (new attacks) can also be utilised to define signatures for abuse detectors. Since previously undiscovered system actions might be categorised as anomalies, this is the fundamental drawback of anomaly-based approaches. Misuse and anomaly

detection are brought together in hybrid detection[4]. In this way, the true positive rate for known intrusions can be raised while the false positive rate for unknown attacks can be lowered. Hybrid approaches make up the vast majority of ML/DL systems.

There are 2 WORKS THAT CONNECT WITH THIS ONE.

As a result of the complexity of sentiment analysis and the strength of machine learning techniques, they have attracted a large number of researchers. Together, sentiment analysis and a thorough examination of machine learning methods enable the development of a cutting-edge intelligent system that can demonstrate its mastery of AI.

However, picking the right machine learning technique may be a daunting task for researchers, and choosing poorly can lead to inaccurate results and subpar model performance. Because of this, we decided to look into comparing the effectiveness of several machine learning methods for sentiment analysis. Only supervised machine learning methods were taken into account, and we attempted to compare them across all of their relevant metrics.

II. LIMITATIONS OF EXISTING SYSTEM

To classify data, an unsupervised learning model must rely on its own intuition when training data lacks labels. Reinforcement Method of Instruction Here, the model is used to inform policymaking. What to do in response to each new piece of information gleaned from the outside world. The model learns via its interactions with the world, which are in turn informed by input it receives from that world. Method of Transduction: It is similar to supervised machine learning, except instead of constructing a function, it makes predictions based on past data as well as current and future information.

III. PROPOSED SYSTEM

Here are the detailed steps of the approach that have been proposed and used in this study. Data Mining Movie Critiques: The fundamental task of any Sentiment analysis study is the collection of data sets; fortunately, several data sets of movie reviews are publicly available online. Purifying the Data: Characters, numbers, special characters, and unrecognised characters make up the movie review data set. Since this could pose a threat to our classifier, we ran a data set cleaning step after we gathered the data sets. The process through which we utilised to clear data sets of any irrelevant information. The next stage, classification of reviews present in the databases, can now begin.

3.1 Data Categorization:

Data that has already been categorised into the available classes can be used with supervised machine learning algorithms. That's why we need to assign label such \sas "Positive" or "Negative" to the reviews according to their characteristics Data Set Preparation for Training and Testing: As with any learning algorithm, a classifier's efficacy is proportional to the time and effort invested into its training and the quality of the data used to teach it. To simplify things, it's usual practise to use 70% of the data set for training and 30% for testing the model.

The Process of Putting the Model Through Training Data Sets: The training phase of sentiment analysis is crucial, as the final results will depend on the methods used to create the classifier. So while training the model it is vital to offer the properly labelled data as its input and also we have to take care the training process should not be overwhelmed. This is because the classifier's performance could suffer if too much time was spent training it. For this reason, we'll make use of the 70% of all available data sets that make up the training data set we created in the previous phase.

3.2 ADVANTAGES OF PROPOSED SYSTEM:

Seven promising supervised machine learning techniques are used to do sentiment analysis of movie reviews in a way that is both straightforward and innovative.

Humans are always working to improve machine intelligence in the hopes that one day it will be able to solve any problem on its own, quickly and effectively. Therefore, we employ machine learning techniques to train and then expect robots to perform.

The discipline of computer science known as "machine learning" (ML) focuses on teaching computers to acquire new skills without being given any specific instructions. The goal is to analyse the movie critics' writing

style and determine if the reviews tend to be positive or negative. This is so due to the fact that moviegoers will only invest their time and money into films that live up to their standards.

Therefore, they used to rely on movie review systems for guidance, reading the comments left by viewers who had previously seen the film in question to determine whether or not to give it a go. There is a need to display or recommend to viewers the percentage of negative and good feedbacks about the relevant movie because it is possible that they will not read all of the comments if there are too many of them. Which will assist the viewer save time and make a better choice overall? The study's goal is to classify the various kinds of movie criticism that exist.

In this way, it may direct users toward reviews of the right kind and, if necessary, provide a breakdown of the amount of good and negative comments for the user's current movie pick (s).

3.3 ARCHITECTURE

Convolutional and subsampling layers are the foundation of a CNN, which can then be followed by fully connected layers. Convolutional layers take as input images of the form (m, m, r) , where (m, m) and (r, r) are the picture's height and breadth and (r, r) are the number of channels, respectively; for example, an RGB image has $r=3$ and $(r, r) = 3$. In the convolutional layer, kk filters (or kernels) will have dimensions of n by n by q by q , where n is less than the image's dimension and q is equal to or less than the number of channels r . Each filter of size $mn+1mn+1$ convolutionally processes the picture to generate a feature map of size kk . The input maps are then subsampled, often using mean or max pooling over $p \times p \times p$ contiguous sections, where p is between 2 and 5 for small images (such as MNIST) and between 2 and 10 for large inputs. Each feature map undergoes an additive bias and sigmoidal nonlinearity either before or after the subsampling layer. Below is an illustration of a complete layer in a CNN, which includes both convolutional and subsampling sublayers. Similar coloured units are equivalent to one another..

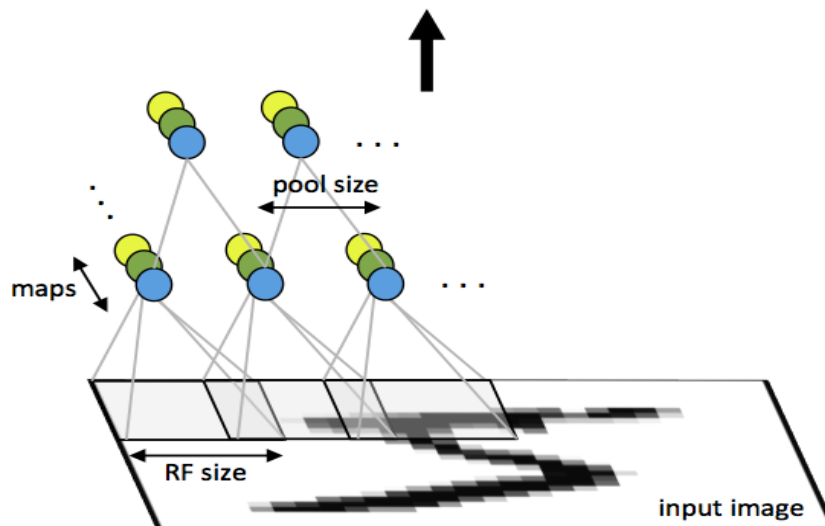


Figure 1: CNN

First layer of a pooled convolutional neural network is shown in Fig 1. The weights of adjacent units are coupled together, and the filter maps are denoted by the colours of the corresponding units.

3.4 Image processing

As discussed before, multilayer perceptrons, which are organised in layers such that each neuron inside a layer receives a copy of all the outputs from the previous layer as its input, are the most general and powerful feedforward neural network model available. Learning from a fixed number of (more or less) unstructured parameters is a challenge that this type of model excels at solving.

But think about what happens to the model's parameter count (weights) when it is fed raw image data. If we treat each channel of each pixel as an independent input to an MLP, then each neuron in the first hidden layer contributes around 3000 additional parameters to the model; CIFAR-10, for example, includes 32323 colored pictures. As the size of the photos increases, the situation becomes uncontrollable very rapidly, long before the

images reach the scale that most people would want to work with in practical applications. Image downsampling to a manageable size for MLP application is a popular workaround. There is a risk of losing a lot of detail if we simply downsample the image, therefore it would be fantastic if we could perform some meaningful processing on the image beforehand, without having to drastically increase the number of parameters..

3.5 Convolutions

It turns out there's a very effective way to do this, and it involves taking advantage of the structure of the information encoded within an image. More specifically, it involves the assumption that pixels that are spatially closer together will "cooperate" on forming a particular feature of interest than pixels that are located in the far corners of the image. In the same vein, if a certain (smaller) characteristic is discovered to be crucial in establishing an image's label, then the placement of this feature within the image is irrelevant.

This is where the convolution operator comes into play. We compute the convolved image $I * K$ by repeatedly superimposing the kernel on top of the image and recording the sum of elementwise products between the image and the kernel, given a two-dimensional image, I , and a small matrix, K , of size $h \times w$, (known as a convolution kernel), which we assume encodes a way to extract an interesting image feature:

$$(I * K)_{xy} = \sum_{i=1}^h \sum_{j=1}^w K_{ij} \cdot I_{x+i-1, y+j-1}$$

(The precise definition really calls for inverting the kernel matrix first, but this step is unnecessary for ML.) To better understand how the preceding formula and convolution (using two different kernels) function as an edge detector, consider the accompanying diagrams:

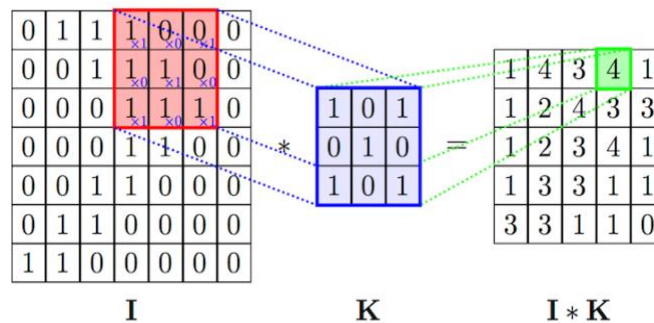


Figure 2: Convolutional and pooling layers

One of the most crucial components of a CNN is the convolution operator, which serves as the basis for the convolutional layer. Layer operation is defined by computing the convolution of the preceding layer's output pictures with each of the specified number of kernels, K (along with additive biases, b per kernel), and then applying the biases (one per each output image). The next step is to apply an activation function, to each pixel in the final images. The final formula of a single output picture channel of a convolutional layer (for a kernel K and bias b) is as follows, where d is the number of channels present in the input to the convolutional layer (for example, red, green, and blue in the input layer).

$$\text{conv}(I, K)_{xy} = \sigma(b + \sum_{i=1}^h \sum_{j=1}^w \sum_{k=1}^d K_{ijk} \cdot I_{x+i-1, y+j-1, k})$$

It's important to keep in mind that, just like the weights of an MLP, the kernels can be learned from a given training dataset through gradient descent, as all we're doing here is adding and scaling the input pixels. Although an MLP could replicate a convolutional layer, it would need significantly more time (and data) in training to learn to operate in a manner that is even remotely close to that of the original.

Finally, it is worth noting that a convolutional operator is not limited to data that is structured in only two dimensions; in fact, most machine learning frameworks (Keras included) will supply you with pre-built layers for 1D and 3D convolutions. Even though the number of parameters in a convolutional layer is much smaller than in a fully connected (FC) layer, more hyperparameters (parameters whose values must be determined before training begins) are included. In particular, inside a single convolutional layer, the following hyperparameters should be selected: How many kernels (and biases) will be convolved with the output of the preceding layer (depth); height and width of each kernel (height and width). The amount by which the kernel is

moved at each iteration to calculate the next pixel in the output is known as the "stride." Typically, this is set to 11, which corresponds with the formula presented before, to specify the overlap between individual pixels in the output. It's important to remember that the output sizes will be reduced with larger strides.

While it is frequently preferable to maintain the same size for both the input and output images, convolution by any kernel larger than 1111 will reduce the size of the output image. In this case, the image is adequately padded with zeroes at the edges. In contrast to "valid" (no) padding, this is often referred to as "identical" padding. While padding of any size is conceivable, same and valid padding are the most common options.

Convolutions are not normally intended to be the only operation in a CNN (although there have been promising recent breakthroughs on all-convolutional networks); rather, they are used to extract important elements of an image before downsampling it sufficiently to be handled by an MLP.

The pooling layer is a widely used method of downsampling images since it combines many independent but equally sized sections of the image (2222). The most common method for performing this aggregation is called "max-pooling," and it involves selecting the highest value of each given pixel inside a given chunk. Below is a graphical representation of the 2222 max-pooling algorithm.

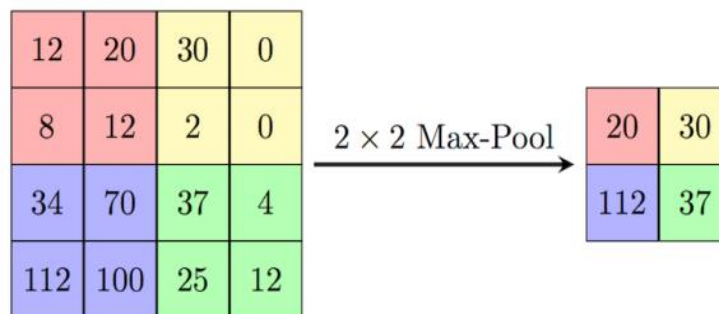


Fig 3: Max pooling

IV. CONCLUSION

In this research, we use seven promising supervised machine learning algorithms to conduct a simple yet new method to sentiment analysis of film reviews. Based on the data, it appears that linear SVC/SVM is the most effective classifier for a large-scale task such as categorising movie reviews with a high degree of certainty.

In the future, we plan to look into its efficiency when applied to large datasets by employing unsupervised and semi-supervised machine learning methods.

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