

TRAFFIC SIGNBOARD AND AMBULANCE DETECTION SYSTEM

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ABSTRACT

The Traffic Signboard and Ambulance Detection System is a Convolutional Neural Network (CNN)-based solution designed to enhance road safety and emergency response. The system optimizes real-time processing, adapts to diverse environmental conditions, and balances accuracy with efficiency. It addresses challenges like computational intensity, false positives and negatives, and model deployment on resource-constrained devices. Seamless integration with existing systems and privacy-preserving measures are key considerations. The goal is to create a robust, ethically sound system capable of accurately detecting traffic signs and prioritizing ambulance recognition for improved overall safety and emergency response.

I. INTRODUCTION

In the ever-evolving landscape of urban transportation, the proliferation of vehicles and the complexity of road networks have given rise to unprecedented challenges in ensuring public safety and efficient traffic management. In response to these challenges, this paper introduces a state-of-the-art Traffic Sign and Ambulance Detection System that leverages the formidable capabilities of Convolutional Neural Networks (CNNs). As cities expand and traffic dynamics become increasingly intricate, there is a pressing need for intelligent systems that can adapt to real-time scenarios and proactively contribute to road safety. The primary motivation behind this research is the compelling requirement to address the multifaceted issues associated with contemporary traffic management. Traditional systems often fall short in coping with the dynamic nature of traffic flows, necessitating the integration of advanced technologies to bring about more responsive and adaptive solutions. The proposed Traffic Sign and Ambulance Detection System is designed not only to augment road safety by accurately recognizing and classifying diverse traffic signs but also to expedite emergency responses by swiftly identifying and prioritizing ambulance vehicles. The overarching objective of the system is twofold. Firstly, it seeks to enhance the awareness of drivers and traffic management authorities by providing real-time, accurate information about the diverse array of traffic signs encountered on the road. Secondly, the system endeavors to contribute to public welfare by enabling rapid and precise detection of ambulance vehicles, ensuring a prioritized and efficient response during emergency situations. The methodology employed in this research centers around the implementation of Convolutional Neural Networks, a powerful class of deep learning algorithms well-suited for image recognition tasks. The CNN is trained on a meticulously curated dataset encompassing a wide spectrum of traffic signs and ambulance images. The utilization of transfer learning techniques further enhances the model's adaptability and efficiency, particularly in scenarios where labeled data might be limited. The significance of this research lies in its potential to revolutionize the landscape of urban transportation management. Accurate traffic sign detection not only aids in preventing accidents but also contributes to the overall efficiency of traffic flow. Concurrently, the swift identification of ambulance vehicles ensures a timely and prioritized response, potentially saving lives in critical situations.

In the subsequent sections, this paper delves into the intricate details of the CNN architecture, the composition and preparation of the dataset, and rigorous experimental validations. Through comprehensive analyses and real-world simulations, we aim to demonstrate the efficacy of the proposed Traffic Sign and Ambulance Detection System, showcasing its potential to significantly enhance road safety and emergency response efficiency in the modern urban environment.

II. LITERATURE REVIEW

Xiong Changzhen, Wang Cong, Ma Weixin, Shan Yanmei [1] "A Traffic Sign Detection Algorithm Based on Deep Convolutional Neural Network", Traffic sign detection plays an important role in driving assistance systems and traffic safety. But the existing detection methods are usually limited to a predefined set of traffic signs. Therefore we propose a traffic sign detection algorithm based on deep Convolutional Neural Network (CNN) using Region Proposal Network (RPN) to detect all Chinese traffic sign. Firstly, a Chinese traffic sign dataset is

obtained by collecting seven main categories of traffic signs and their subclasses. Then a traffic sign detection CNN model is trained and evaluated by fine-tuning technology using the collected dataset. Finally, the model is tested by 33 video sequences with the size of 640×480. The result shows that the proposed method has towards real-time detection speed and above 99% detection precision. The trained model can be used to capture the traffic sign from videos by on-board camera or driving recorder and construct a complete traffic sign dataset. This paper has presented a Chinese traffic sign detection algorithm based on deep convolutional neural network using region proposal network in Faster R-CNN. The method can detect all seven main categories Chinese traffic sign. We trained and compared three models. The experimental results show that the traffic sign detection rate of our algorithm is above 99% and the detection time is towards real-time in video sequences. The trained model can be used to capture the traffic sign in the videos or images from the web and generate a complete dataset about traffic signs through simple postprocessing, therefore this method is of great significance in terms of data collection of traffic signs.

Xu Zhe¹, Ren Jingyi¹, Bao Chaoqian,¹ "Wavelet Transform to Improve Accuracy of a Prediction Model for Overall Survival Time of Brain Tumor Patients Based On MRI Images", [2] In this paper, a simple and efficient algorithm for detecting deformed and occlusion triangular and circular traffic signs under complex natural scenes is proposed. Firstly, the image is segmented and binarized. Then the convex hull of every contour extracted from the binarized image is calculated. Some concave part of a contour is removed and is replaced by the corresponding convex edge of the convex hull. After that, the contour is approximated to a polygon. Finally, Those contours which can be succeed to approximated to a triangle is the triangular traffic signs, and other contours approximation which can be approximated to a ellipse with random least squares fitting is the circular traffic signs. The experimental results shows the detection rate reaches 86.79%, this algorithm can handle the adverse influence of traffic signs' deformation, occlusion better than hough method. It has better real-time performance and lower error detection rate than template method. In this paper, a triangular and circular detection algorithm based on the removal of the depression and the contour approximation is proposed.

Experiments show that the algorithm has higher real-time performance and lower false positive rate than the template method, which has a higher detection rate for Hough, and has better adaptability to the motion blur scene. But the algorithm for circular traffic sign's error detection rate is still high, it needs further improvement. Shuang Wu¹, Chenglu Wen^{1*}, Huan Luo,¹ "using mobile lidar point clouds for traffic sign detection and sign visibility estimation", [3] This paper presents a novel method for traffic sign detection and visibility evaluation from mobile Light Detection and Ranging (LiDAR) point clouds and the corresponding images. Our algorithm involves two steps. Firstly, a detection algorithm based on high retro-reflectivity of the traffic sign from the MLS point clouds is designed for sign detection in complicated road scenes. To solve the spatial features of traffic signs, we also create geo-referenced relations between traffic signs and roads according to the normal of ground. Secondly, we propose a visibility estimation method to evaluate the visibility level of the traffic sign based on a combination of visual appearance and Spatial related features. The proposed algorithm is validated on a set of transportation-related point-clouds acquired by a RIEGL VMX-450 LiDAR system. The experiment results demonstrate that the efficiency and reliability of the proposed algorithm in detection traffic signs are robust, and also prove the potential of using mobile LiDAR data for traffic sign visibility evaluation. This paper proposed a novel traffic sign detection and visibility estimation method, which integrates the spatial-related features and image features extracted from point clouds and images. The visibility estimation results by our method match the subjective evaluation results well. The experimental results demonstrated that the proposed method has a potential to estimate the visibility of traffic sign.

"Automatic Detection And Classification Of Traffic Signs", [4] This paper proposes algorithms for the automatic detection of traffic signs from photo or video images and their classification to provide a driver alert system. Several examples taken from Portuguese roads are used to demonstrate the effectiveness of the proposed system. Traffic signs are detected by analyzing color information, notably red and blue, contained on the images. The detected signs are then classified according to their shape characteristics, as triangular, squared and circular shapes. Combining color and shape information, traffic signs are classified into one of the following classes: danger, information, obligation or prohibition. Both the detection and classification algorithms include innovative components to improve the overall system performance. This paper proposed an automatic traffic

sign detection and classification system. New contributions are included for the validation of sign detections, as well as for the classification stage, namely by including a simple, yet effective, algorithm for square and triangle identification. As expected, correct traffic sign detection is essential for accurate classification. As future work, the detection algorithm will be improved to better handle images with critical illumination conditions, such as those obtained from night driving. Also improved classification for STOP signs and the recognition stage will be added. For normal illumination conditions, the algorithm already shows good performance in terms of detection and classification.

Bao Trung Nguyen, JaeRyong, Shim. "Fast Traffic Sign Detection under Challenging Conditions", [5] In recent years, a lot of researches on traffic sign detection and recognition have been done. But most of them were tested under restricted conditions such as camera with high resolution and sensitivity, highway environment or road side having a lot of trees and very few distracting objects. In this paper, we present a fast and robust traffic sign detection system including two main stages: Segmentation and detection. To boost the reliability of system, a flexible segmentation stage is designed, which includes double segmentation, one with higher criteria and the other with lower criteria, to reliably cut down a great Computation burden for the shape-based detection. The accuracy rate is tested to be at least 86.7% in challenging conditions, and mostly not to miss a case in usual illumination with image sequences. The dataset used in experiments is recorded with a VGA camera under diverse lighting conditions, from dark or cloudy sky to glaring condition, in urban area where a lot of confusing objects appearing on road side and target objects in few cases are partially occluded. An automatic real-time system for detecting traffic sign has been shown and demonstrated successfully. The system is a flexible solution for traffic sign detection problem. The segmentation stage is designed from a classical idea of region growing. On the other hand, shape detection take advantage of color characteristics of traffic signs. Both stages support in limiting disadvantages of each other, thereby increasing overall system performance and accuracy. The system is proved to work robustly at approximately 92.5% in varying conditions of lighting, urban roads without trees on road side and with a low dynamic range camera.

Ying Li¹, Lingfei Ma¹, Yuchun Huang³, Jonathon Li, "Segment-Based Traffic Sign Detection From Mobile Laser Scanning Data", [6] This paper presents a segment-based traffic sign detection method using vehicle-borne mobile laser scanning (MLS) data. This method has three steps: road scene segmentation, clustering and traffic sign detection. The non-ground points are firstly segmented from raw MLS data by estimating road ranges based on vehicle trajectory and geometric features of roads (e.g., surface normal and planarity). The ground points are then removed followed by obtaining non-ground points where traffic signs are contained. Secondly, clustering is conducted to detect the traffic sign segments (or candidates) from the non-ground points. Finally, these segments are classified to specified classes. Shape, elevation, intensity, 2D and 3D geometric and structural features of traffic sign patches are learned by the support vector machine (SVM) algorithm to detect traffic signs among segments. The proposed algorithm has been tested on a MLS point cloud dataset acquired by a Leader system in the urban environment. The results demonstrate the applicability of the proposed algorithm for detecting traffic signs in MLS point clouds. This paper proposed a segment-based traffic sign detection method, which integrates 2D and 3D geometric and structural features extracted from clustered segments. As can be seen from the detected traffic signs in different situations, we conclude that the proposed segment-based algorithm performs robustness and achieves reliable results.

Li Lei-min¹, Li Li², Tong Ru-qiang³, Li Pei-xi, "Feature Detection and Matching for Traffic Sign Image", [7] Chatbots are special agents that respond with the user in natural language just as a human would reply. Specifically, social chatbots are the ones which establish a strong emotional relationship with the user. The main concept behind this chatbot was to provide mental relief to students who undergo different levels of stress and which can be the onset of an inimical depression. In this paper, we proposed an intelligent social therapeutic chatbot which distributes the text into emotion labels namely, Happy, Joy, Shame, Anger, Disgust, Sadness, Guilt, and Fear. Further, based on the emotion label, it identify the users' mental state such as stressed or depressed using users' chat data. For emotion detection, we deployed three popular deep learning classifiers namely, Convolutional Neural Network (CNN), Recurrent Neural Network (CNN), and Hierarchical Attention

In order to identify emotion of user chat text, three deep learning algorithms namely, CNN, RNN and HAN were deployed. With the help of label of emotion, it also identifies the mental state of the user such as stressed or

depressed. In the future, we will increase accuracy for text classification methods. Currently, we have focused on minor details of the user as we believe that attending to their queries and alleviating them from the stress would be the need more information about the user would lead to an efficient and desired output.

Md Tarequl Islam, "Traffic sign detection and recognition based on convolutional neural networks", [8] Traffic sign detection and recognition topic are one of the most popular topics of computer vision and image processing in recent years, as they play an important role in autonomous driving and traffic safety. This paper proposes a system that will detect and classify different types of traffic signs from images. This paper differs from other papers as it uses signs that are globally recognized and isn't limited to very few signs like many other papers.

The number of signs used in this paper for classification is 28, which are used all around the globe. Two separate neural networks have been used for detection and recognition purpose; one classifies the sign and other the shape.

Image augmentation has been used to create the training and validation dataset. 40,000 images have been used to train the first classifier with 28000 positive images (images that contain the traffic signs) and 12000 negative images (images that do not contain any traffic signs) and 3600 images were used to train the second classifier with 2400 positive images and 1200 negative images. The images are processed to find the region of interest, which is then fed to two CNN classifiers for classification.

Shuang Wu, Chenglu Wen, Huan Luo, Yiping Chen, Cheng Wang and, Jonathan Li, "USING MOBILE LIDAR POINT CLOUDS FOR TRAFFIC SIGN DETECTION AND SIGN VISIBILITY ESTIMATION" , [9] paper presents a novel method for traffic sign detection and visibility evaluation from mobile Light Detection and Ranging (LiDAR) point clouds and the corresponding images. Our algorithm involves two steps. Firstly, a detection algorithm based on high retro-reflectivity of the traffic sign from the MLS point clouds is designed for sign detection in complicated road scenes. To solve the spatial features of traffic signs, we also create geo-referenced relations between traffic signs and roads according to the normal of ground. Secondly, we propose a visibility estimation method to evaluate the visibility level of the traffic sign based on a combination of visual appearance and spatial-related features. The proposed algorithm is validated on a set of transportation-related point-clouds acquired by a RIEGL VMX-450 LiDAR system. The experiment results demonstrate that the efficiency and reliability of the proposed algorithm in detection traffic signs are robust, and also prove the potential of using mobile LiDAR data for traffic sign visibility evaluation.

III. MOTIVATION

The motivation behind developing a Traffic Sign + Ambulance Detection System using CNN stems from the critical need to bolster road safety and emergency response mechanisms. With the escalating complexity of urban traffic scenarios, there is a growing demand for intelligent systems that can swiftly and accurately interpret and respond to vital cues on the road. Traffic signs serve as indispensable guides for drivers, and their prompt recognition is paramount for safe navigation. This project is driven by the vision of creating a safer and more responsive road environment, where cutting-edge technology contributes to a reduction in accidents and facilitates swifter emergency interventions.

IV. PROBLEM STATEMENTS

The purpose of the CNN-powered Traffic Sign + Ambulance Detection System is to use cutting-edge deep learning techniques to identify and classify traffic signs and ambulances in real-time. The system's goals include overcoming difficulties with computation complexity, adapting to a variety of situations, and integrating seamlessly with current traffic control systems. Its use includes raising traffic flow, accelerating emergency response times, and improving road safety by offering a precise and effective means to identify crucial features on roads in a timely manner.

V. ALGORITHM

CONVOLUTIONAL NEURAL NETWORK

Deep Convolutional Neural Networks (CNNs) consist of several layers that collectively enable effective feature extraction and hierarchical learning. The fundamental building blocks include convolutional layers, pooling layers, and fully connected layers. Convolutional layers are the core components responsible for detecting

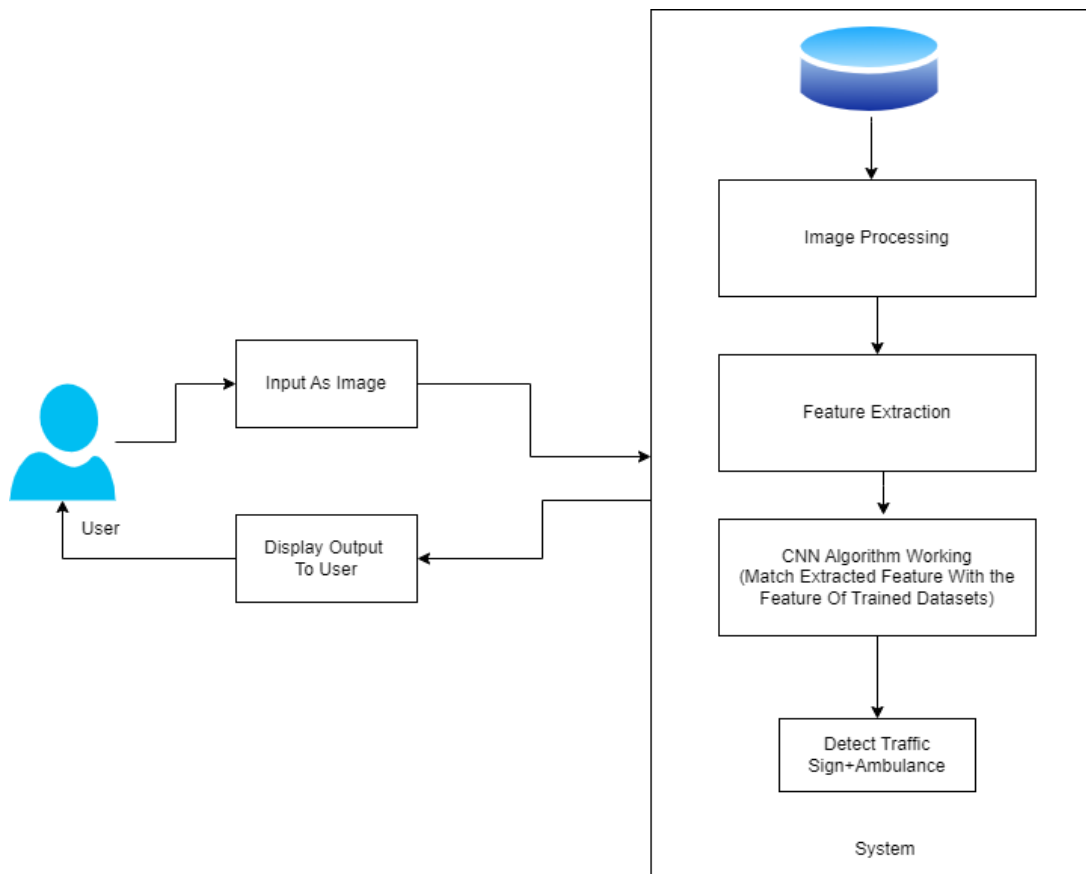
spatial patterns and features within the input data, utilizing convolutional filters that slide over the input to extract relevant information. These layers are often followed by activation functions like ReLU (Rectified Linear Unit) to introduce non-linearity to the model.

Pooling layers, such as max pooling or average pooling, contribute to spatial downsampling, reducing the spatial dimensions of the feature maps while retaining essential information. This helps manage computational complexity and enhance the network's ability to capture distinctive features. Additionally, pooling aids in creating a degree of translational invariance, making the network more robust to variations in object positions within the input.

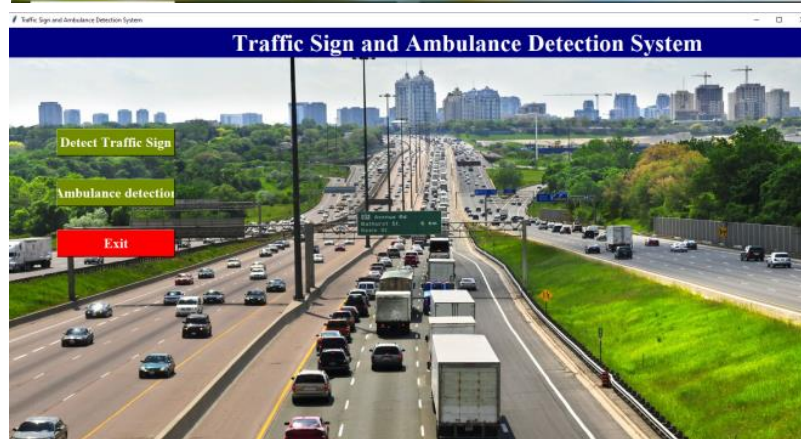
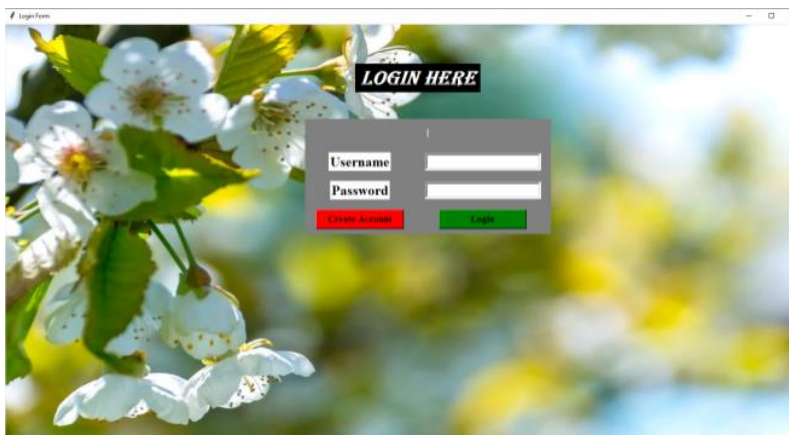
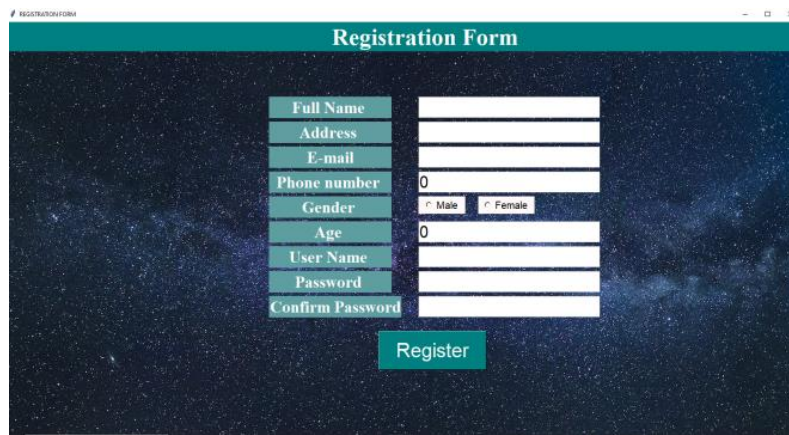
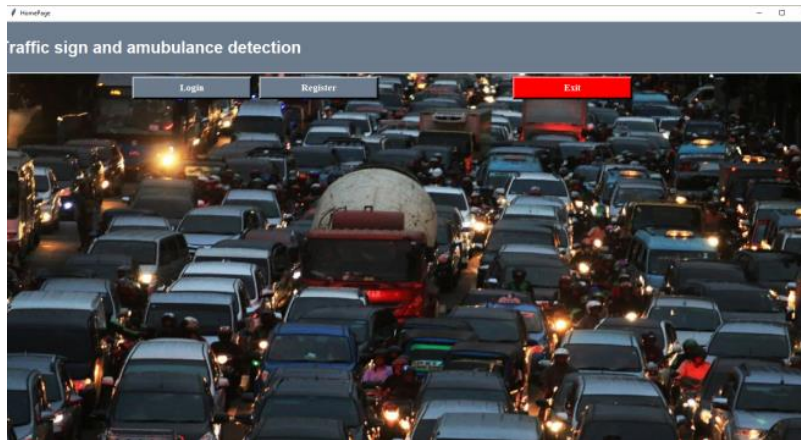
Fully connected layers come into play towards the end of the network, aggregating the high-level features learned by the previous layers and mapping them to the output classes. These layers connect every neuron to every neuron in the subsequent layer, enabling the network to make intricate associations and predictions. To avoid overfitting, dropout layers may be incorporated, randomly disabling a fraction of neurons during training. The depth of these networks, often referred to as the network's "depth" or "architecture," is a key aspect of their success. Deep CNN architectures, such as VGG16, ResNet, and Inception, have demonstrated the importance of increased depth in capturing complex hierarchical features, allowing for state-of-the-art performance in various computer vision tasks like image classification and object detection. Overall, the interplay of these layers in deep CNNs contributes to their ability to learn intricate representations and patterns from input data, making them powerful tools in image analysis and recognition tasks.

VI. SYSTEM ARCHITECTURE

A system architecture is the conceptual model that defines the structure, behavior, An architecture description is a formal description and representation of a system, organized in a way that supports reasoning about the structures and behaviors of the system. A system architecture can consist of system components and the sub-systems developed, that will work together to implement the overall system. There have been efforts to formalize languages to describe system architecture, collectively these are called architecture description languages



VII. RESULTS





VIII. CONCLUSION

In conclusion, the application of a CNN algorithm for traffic sign detection and ambulance recognition demonstrates a robust and promising capability in various real-world scenarios. The model exhibits high accuracy in effectively localizing and classifying traffic signs, showcasing its proficiency in traffic management systems. However, challenges arise in complex situations with adverse weather conditions or occlusions, leading to occasional false positives or negatives. The algorithm's ability to sensitively and specifically detect ambulances proves crucial for emergency response scenarios. Despite these achievements, there is room for improvement, particularly in enhancing the model's robustness to challenging environmental factors. The findings suggest that further fine-tuning and optimization may be beneficial to elevate the algorithm's performance, ensuring its reliable deployment in practical applications, such as traffic management and emergency services.

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